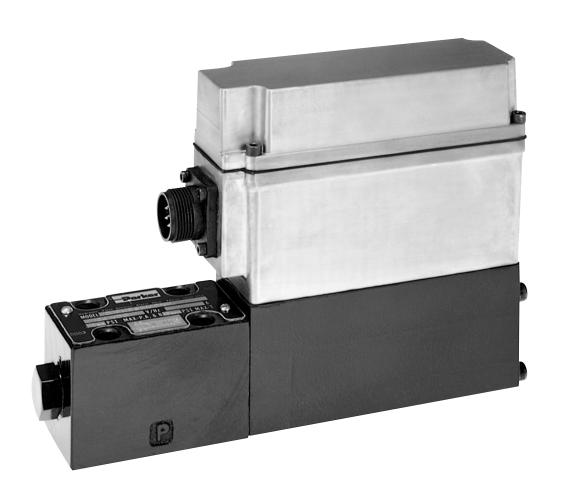


Bulletin HY14-2579-M1/US Installation Guide

Series D1FH Proportional Directional Control Valves

Effective: February 1, 2001 Supersedes: April 1, 2000



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d1fh-cvr.p65, dd, cm



Contents

Technical Information	1
General Description	1
Operation	1
Features	1
Specifications	1
Interface Wiring	2
Valve Type - D1FHE***C*BJ00 "B" Version	2
Installation	2
Figure 1 – Configurations	2
Interface Wiring - 7 Pin Connector	2
Figure 2 – Interface Wiring Diagram (7 Pin)	2
EHC 8G Cable Wiring	2
Initial Start-up	3
Jumpers	3
Initial Start-up	3
Figure 3 – Board Setup	3
Figure 4 – Functional Block Diagram	3
Installation Information	5
Ordering Information	6
Offer of Sale	7

Technical Information

General Description

The Parker D1FH is a high response proportional servo valve with an on-board drive amplifier. The D1FH incorporates the use of state-of-the-art drive electronics with an LVDT for continuous monitoring of the spool position. Zero lap spools are available for closed loop applications with two different 'power down' configurations. The valve features frequency response levels greater than 100 Hz, along with low hysteresis and excellent repeatability.

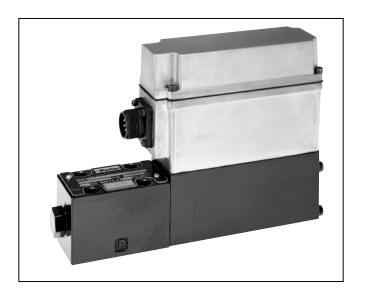
Operation

The D1FH valve uses a precision lapped spool and sleeve configured with four control positions. During normal operation the valve will shift from the center position to either side providing flow out the 'A' or 'B' port. When input power is removed from the drive amplifier, the valve will shift to a fourth position. The fourth position will block all four ports in one version. A second version that is available will block the 'P' port and allow the 'A' and 'B' ports to bleed to the 'T' (tank line). (Refer to the 'enable' note on page 4.)

Note: The tank line to the valve must have a minimum pressure of 1.4 Bar (20 PSI). Maximum pressure is 35 Bar (500 PSI).

Features

- On-Board Electronic Drive Amplifier Integral electronics eliminates the need for costly wiring between the valve and driver card. The unit is shipped as a factory preset and tested unit.
- High Frequency Response The valve has a very high frequency response which is necessary for many closed loop applications.
- Four Position Spool Capability The four position spool provides predictable flow in the event of a power failure to the drive electronics, within the limits of the power curve.
- 315 Bar Pressure Capability The maximum operating pressure rating for the D1FH is 315 Bar or 4500 PSI (40 LPM version limited to 210 Bar).
- Spool Position Feedback The LVDT continuous feedback monitoring circuit provides low hysteresis and excellent repeatability.
- Contaminant Sensitivity The D1FH operates with standard mineral oil based fluids with a cleanliness level of ISO Class 16/13, SAE Class #4.
- Drive Enable Feature Output to the coil is shut down when the enable signal, (5 to 30 VDC), is not present.
 The valve will then shift to the fourth position flow path selected by the user.
 (See note on page 4.)



Specifications

Interface	NFPA D03, CETOP 3	
Max. Operating Press.	315 Bar (4500 PSI)	
Max. Tank Line Press.	35 Bar (500 PSI)	
Min. Tank Line Press.	1.4 Bar (20 PSI)	
Flow Rating at ∆p 35 Bar (500 PSI) per metering edge	B spool 5 LPM (1.3 GPM) D spool 10 LPM (2.6 GPM) H spool 20 LPM (5.3 GPM) M spool 40 LPM (10.6 GPM)	
Typical Spool Overlap	Zero Lap	
Pressure Gain % of Change/1% Change in Command	Typical 40% Minimum 25%	
Frequency Response	> 100 Hz at 5% spool stroke (-3 dB)	
Step Response	< 16 ms at 100% signal	
Hysteresis	< 0.5%	
Repeatability	< 0.5%	
Viscosity Range	15 to 65 cSt (75 to 300 SSU)	
Fluids	Mineral base hydraulic fluid	
Operating Temp. Range (Ambient)	0 to 60° C (32 to 140° F)	
Fluid Cleanliness Level	ISO Class 16/13, SAE Class #4 or better	
Power Requirements	24 VDC, +20%, -10% 2 amps average 4.0 amps peak (<10 ms)	
Command Signals	± 10 VDC at 100 k ohm input impedance	
	± 20 mA at 499 ohm input impedance	
Protection Class	IP65, NEMA 12	



Ordering Information

Valve Type D1FH

This valve operates using a 24 VDC supply, accepts a \pm voltage or current command and interfaces to the system through a 7 pin I/O connector located on the conduit box.

Installation

Refer to the back of the manual for fluid recommendations, mounting restrictions and other general installation instructions.

Refer to Bulletin No. 2579-000-2/USA for the performance curves and valve dimensions for the D1FH.

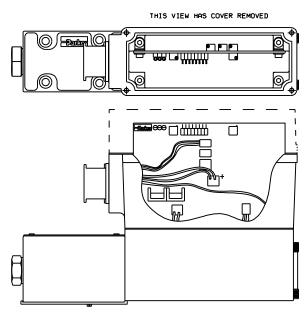
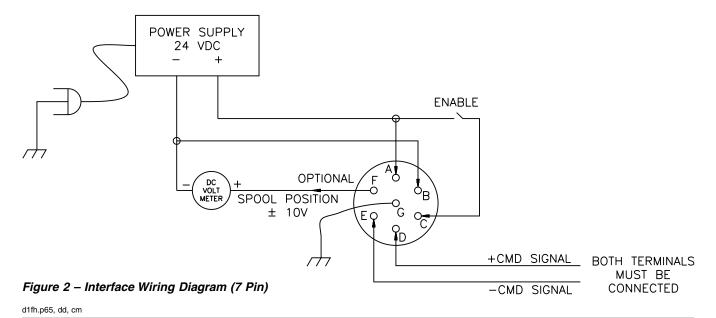


Figure 1 - Configurations

Interface Wiring - 7 Pin I/O Connector

Power Supply	24 VDC Nominal 2.0 Amps 4.0 Amps Peak (<10 ms) + to Pin A - to Pin B
Enable	5 to 30 VDC at Pin C No signal disables the valve.
Command Input	±10 VDC between Pin D and Pin E If D is more positive than E, flow is from P→A. Note: If command source is not differential tie the unused input to the command source common.
Spool Position Output (optional)	Pin F ±10 VDC Positive voltage is P→A. Negative voltage is P→B.
Chassis Ground	Pin G, internally wired to the valve body.

EHC 8G Cable Wiring			
<u>PIN</u>	<u>FUNCTION</u> <u>COLOR</u>		
A	+Pwr Sup Red		
В	B Pwr Sup Com		
С	Enable	Yel	
D	+Cmd	Blue	
E	-Cmd	Orn	
F	Spool	Wht	
G	Chassis Gnd	Grn	
I			





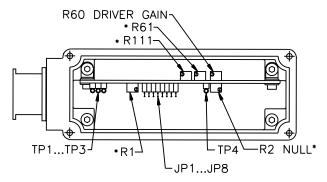
Initial Startup

The following procedure is for start up only. Once the valve is in the system and operating this will not be required.

- Mount valve keeping contamination to a minimum. We suggest you install a 1.4 Bar (20 PSI) check valve in the T port line. (Solenoid Up not recommended.)
- Run oil to the valve with the electronics off, allowing the valve body to heat up and acclimatize to hot oil temperatures. (Turn on the power to valve with Enable Signal removed.)
- 3) Always start with the system gain at minimum this is the external closed loop gain of your computer or PLC. If the system gain is too high the valve will oscillate and could pull in air. With the gain low, apply the Enable signal. The Enable signal has a 10 mS time delay to allow the electronics to stabilize. During the transition with a OV or OmA command signal, the valve will go through the
 - P-B, A-T position while traveling to the functional center position of the valve.
- 4) If the valve oscillates check your command inputs for noise or air in the system.
- Once the valve is stabilized, adjust R60 CW for maximum performance.
- 6) Run valve through a series of repeat cycles, in and out for 5 minutes. Adjust the gain as required for system performance. If the speed is different for extend and retract it probably means you need to set different gains in your controller for extend and retract.

Jumpers

Command Input	Jumper Selection
±10 VDC	JP2 IN JP4 IN JP7 SPARE
±20 mA	JP1 IN JP2 IN JP4 IN



* Factory Adjustments - DO NOT ADJUST

Figure 3 - Board Setup

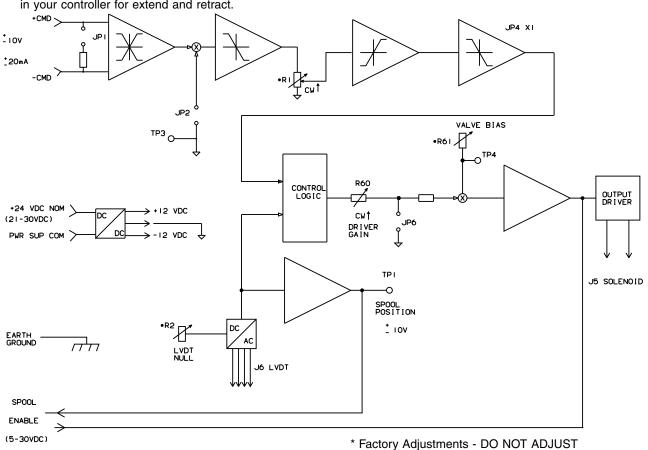


Figure 4 - Functional Block Diagram



Trouble-shooting

Symptom	Cause	Solution
Instability	Power Supply?	Select a power supply not current limited below 4.0 Amps. Use a separate power supply for each valve. The power supply must be chassis grounded.
	Noise on inputs?	To verify, remove input signals and short +CMD to -CMD. For best noise immunity, connect input signals (2 wires for each input) directly to the command source. This is a high bandwidth valve so 60 hertz noise at the inputs could be amplified.
	System Gain?	Initial startup should be with the external feedback loop gain at a minimum value and lower pressure. Oscillation may be a result of high loop gain. (Note: with motion controllers minimum gain may less than one).
	Oil Temperature?	The oil temperature should be within the 38° C to 60° C (100° F to 140° F) range. (Viscosity range = 15 to 65 cSt or 75 to 300 SSU).
	Air in valve?	High frequency operation with low tank line pressure could result in air in the valve. The suggested tank line pressure is a minimum of 20 PSI. To eliminate air, apply a low pressure and cycle the valve at a low frequency with a command of approximately ± 10 VDC (or ± 20 mA).
Null	System Variations?	The valve was nulled for a double rod cylinder. The external closed loop system gain should compensate for load variations and provide the error signal required for null. With closed loop control removed, actuator may drift. Circuit may require an idle mode manifold.
Low Flow	Flow Limited?	Verify potentiometer R1 is fully CW. Verify that the Command input is +10 VDC or -10 VDC for maximum flow.
	Floating Input?	Both inputs terminals must be connected. If only one terminal is used, tie the other terminal to command source common.
		System pressure? Verify that the system pressure is set as required and there are no other flow paths.
No Flow	Power?	Verify there is power to the board and it is wired with the correct polarity.
		Verify that the ENABLE signal is present.
		Verify that the connections to the valve subplate are correct.
Full Flow	Phasing?	If connected to an external feedback system, verify open loop operation of valve with a potentiometer. Improper system phasing would result in maximum Command input.
Cylinder Extended/ Retracted and Won't Return	Phasing?	System phasing is incorrect. Try reversing the system Cmd or Fdbk inputs.
Flow With No Enable	System Dynamics?	The spool will return to the fourth position only if the system dynamic flows and pressures are within the power capacity envelope. The fourth position is subject to all Bernoulli flow forces, radial hydraulic lock forces and other forces that affect all directional control valves. The system designer must determine if the dynamic flows and pressures in the system will prevent the spool from returning to the fourth position. This would have to be verified with full load testing.
d1fh.p65, dd, cm		As with any spool valve, the user should not rely on the valve to hold loads in place. The leakage rate through the fourth position blocked center spool (80 spool) will allow an unloaded single rod cylinder to extend. This occurs with any blocked center four-way valve.



Installation Information

FOR MAXIMUM VALVE RELIABILITY, ADHERE TO THE FOLLOWING INSTALLATION INFORMATION

Fluid Recommendations

Premium quality hydraulic oil with a viscosity range between 32-54 cSt (150-250 SSU) at 38°C (100°F) is recommended. The absolute operation viscosity range is from 15-65 cSt (75-300 SSU). Oil should have maximum anti-wear properties and rust and oxidation treatment.

Filtration

For maximum valve and system component life, the system should be protected from contamination at a level not to exceed 125 particles greater than 10 microns per milliliter of fluid. (SAE Class 4 or better/ ISO Code 16/13). Flushing the system prior to valve installation is recommended on new installations.

Silting

Silting can cause any sliding spool valve to stick, and not spring return, if held shifted under pressure for long periods of time. The valve should be cycled periodically to prevent sticking.

Special Installations

Consult your Parker representative for any application requiring the following:

- Pressure above rated.
- Fluid other than those specified.
- Synthetic or fire-resistant fluids.
- Oil temperature above 71.1°C (160°F).
- Flow path other than normal.
- Non-standard power supply grounding.

Torque Specifications

The recommended torque values are for the bolts which mount the valve to the manifold or subplate are as follows:

NFPA Size	Bolt Thread Size Metric English		Torque
D03	M5 x 0.8	10-24 UNC	5.6 N.m. (50 inlbs.)

Mounting Restriction

In order to ensure proper operation, the D1FH must be mounted horizontally. If the valve is mounted vertically, a check valve with a minimum rating of 1.4 Bar (20 PSI), should be placed in the tank line to maintain back pressure to the valve.

Tank Line Surges

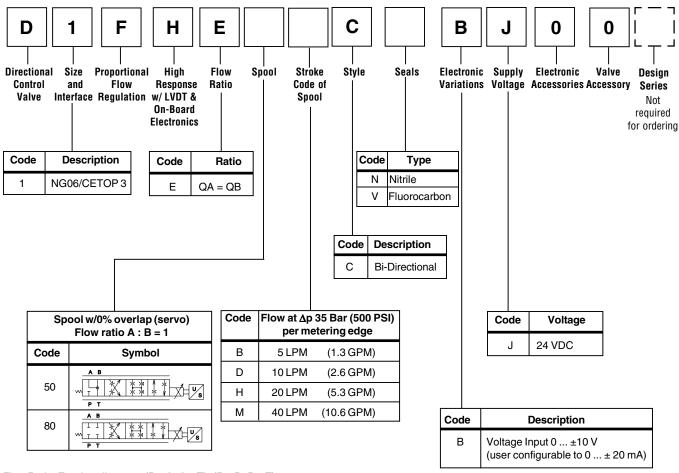
If several valves are piped with a common tank line, flow surges in the line may cause an unexpected spool shift. Separate tank lines should be used when line surges are expected.

Subplate Specifications

Subplate	Port Size	Location	Max. Pressure
SPD23	3/8" NPTF	Bottom	207 Bar (3,000 PSI)
SPD2330	3/8" NPTF	Bottom	345 Bar (5,000 PSI)
SPD23S	9/16-18 NPTF	Bottom	207 Bar (3,000 PSI)
SPD23SA	9/16-18 NPTF	Side	207 bar (3,000 PSI)



Ordering Information



Flow Ratio: $E = \text{throttling area } (P \rightarrow A = A \rightarrow T) = (P \rightarrow B = B \rightarrow T)$

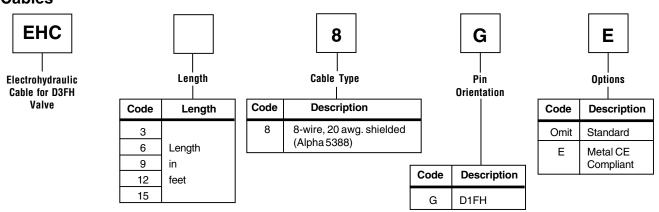
Use one Power Supply for each valve. #PS24

Connector — Part #697323 (7 pin CE)
Part # (7 pin CE)

Mounting Bolt Kit — #BK209 Metric #M5X30 (qty 4)

Weight: NG06 3.7 kg (8.2 lbs.)

Cables





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- 8. Buyer's Property: Any designs, tools, patterns, materials, drawings, confidential information or equipment furnished by Buyer or any other items which become Buyer's property, may be considered obsolete and may be destroyed by Seller after two (2) consecutive years have elapsed without Buyer placing an order for the items which are manufactured using such property, Seller shall not be responsible for any loss or damage to such property while it is in Seller's possession or control.
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